



The Future of Analog IC Technology®

# EV6513L-J-00A

0.6A, 5.5V  
Full H-bridge Motor Driver  
Evaluation Board

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## DESCRIPTION

The EV6513L-J-00A is an evaluation board for the MP6513LGJ. It is a full-H-bridge motor driver used for driving reversible motors, which can drive one dc motor or one winding of a stepper motor or other loads.

It operates from a supply voltage range of 2.5V to 5.5V and can deliver motor current up to 0.6A.

The input control signals for the MP6513LGJ are applied through the connector.

## ELECTRICAL SPECIFICATIONS

| Parameter              | Symbol    | Value   | Units |
|------------------------|-----------|---------|-------|
| Input Voltage          | $V_{CC}$  | 2.5-5.5 | V     |
| Maximum Output Current | $I_{OUT}$ | 0.6     | A     |

## FEATURES

- Wide 2.5V to 5.5V Input Voltage Range
- 0.6A continuous driver current
- Full-H-bridge motor drive
- OCP, OVP, and OTP

## APPLICATIONS

- Cameras
- Toys
- Consumer Products
- Medical Devices

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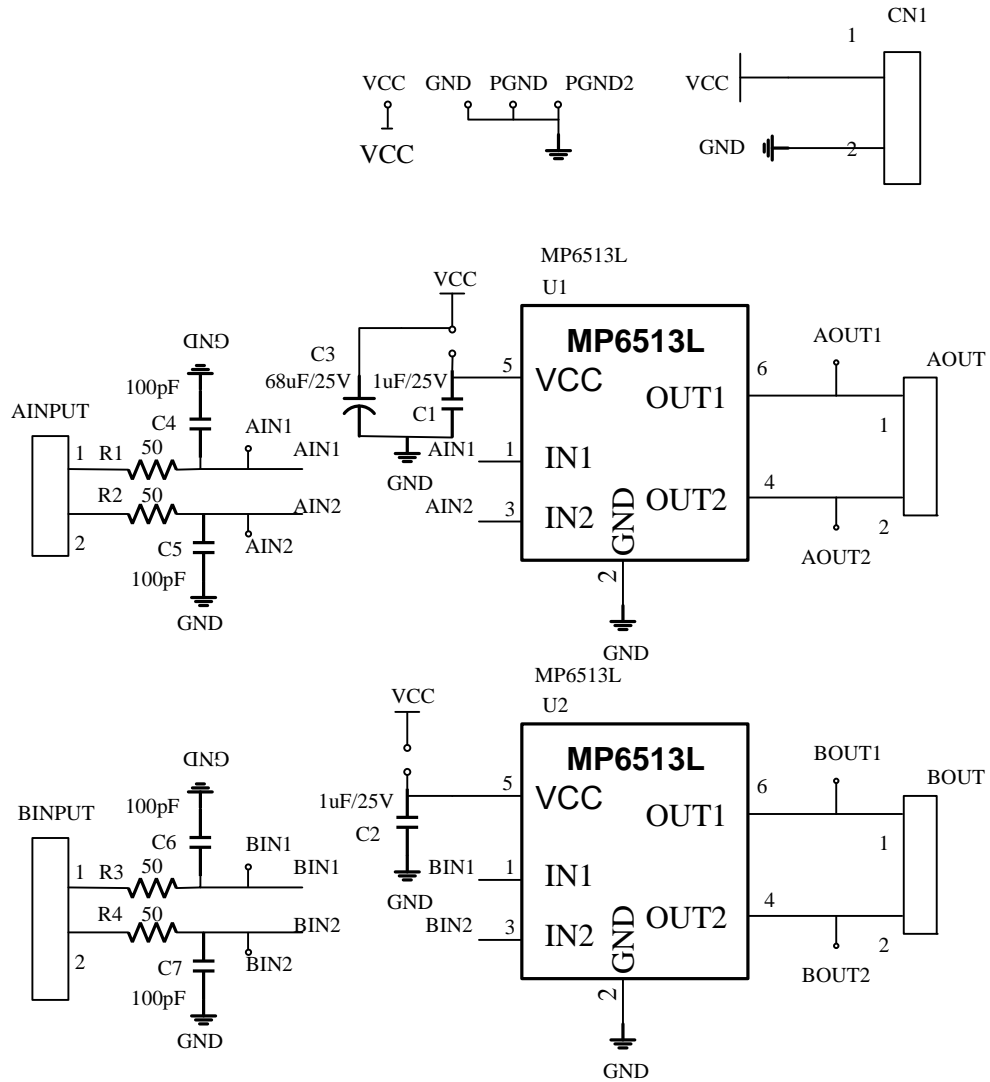
## EV6513L-J-00A EVALUATION BOARD



(L x W x H) 6.35cm x 6.604cm x 1.8cm

| Board Number  | MPS IC Number |
|---------------|---------------|
| EV6513L-J-00A | MP6513LGJ     |

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**EVALUATION BOARD SCHEMATIC**



**Figure 1 .Schematic of EVB**

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**EV6513L-J-00A BILL OF MATERIALS**

| Qty | Ref   | Value          | Description                         | Package    | Manufacturer | Part Number        |
|-----|---|----------------|-------------------------------------|------------|--------------|--------------------|
| 2   | C1,C2   | 1 $\mu$ F/25V  | Ceramic Capacitor;<br>25V;X7R       | 0805       | muRata       | GRM21BR71E105KA99L |
| 1   | C3  | 68 $\mu$ F/25V | Ceramic Capacitor;50V               | DIP        | Panasonic    | EEU-FCIH680        |
| 4   | C4,C5,C6,C7   | 100pF          | Ceramic Capacitor;<br>50V;C0G;      | 0603       | muRata       | GRM1885C1H101JA01D |
| 4   | R1, R2, R3,R4   | 49.9           | Film Resistor;1%                    | 0603       | Yageo        | RC0603FR-071KL     |
| 3   | CN1,<br>CN2,<br>CN3                                       |                | CONN/2PIN/5.08MM                    | DIP        |              |                    |
| 2   | AINPUT,<br>BINPUT,AIN1,<br>AIN2,<br>BIN1,<br>BIN2,<br>GND | CONNE<br>CTOR  | SIP 2.54mm *<br>40 PIN<br>CONNECTOR | Radial     | ANY          |                    |
| 2   | JP1,JP2   | CONNE<br>CTOR  | SIP 2.54mm *<br>40 PIN<br>CONNECTOR | Radial     | ANY          |                    |
| 8   | AOUT1,<br>BOUT1,<br>AOUT2,<br>BOUT2,GND*<br>3,VCC         | TP             | 1mm GOLD<br>PLATED<br>TEST POINT    | Radial     | ANY          |                    |
| 2   | U1,U2   | MP6513L<br>GJ  | MP6513LGJ<br>R6                     | FCTSOT23-6 | MPS          | MP6513LGJ          |

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PRINTED CIRCUIT BOARD LAYOUT

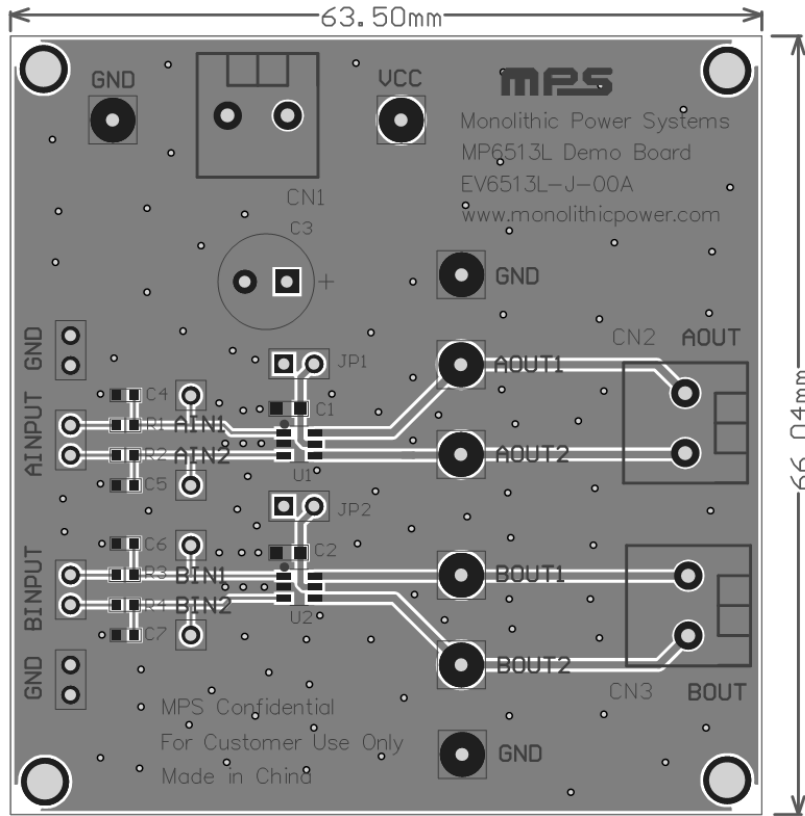


Figure 2 .Top Layer

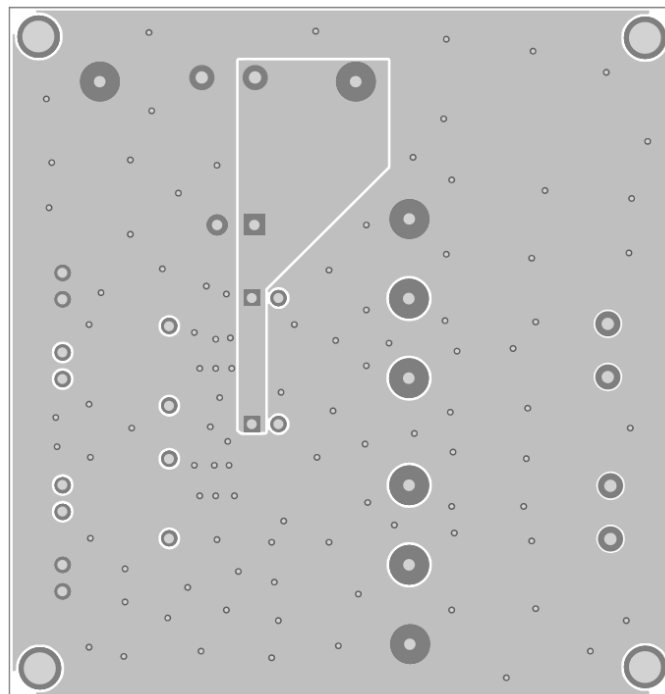


Figure 3 .Bottom Layer

## QUICK START GUIDE

This board is set up from the factory for 2.5V to 5.5V operation.

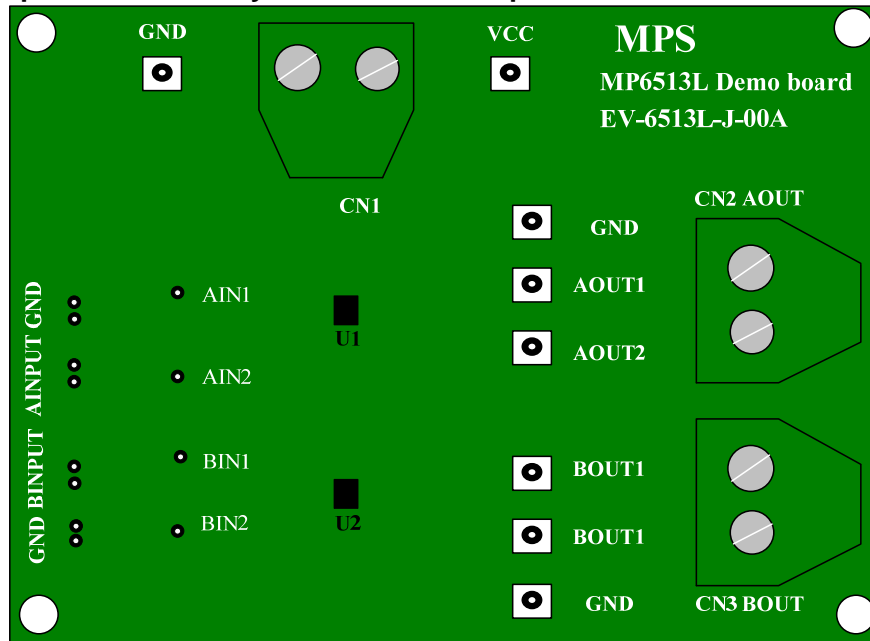


Figure 3. Input and Output Terminals of EV6513L-J-00A

### 1. Applications

This evaluation board can be used to control two single-phase DC motor independently or a stepper motor by corresponding input signals. The recommended supply voltage is range from 2.5V to 5.5V, and the maximum drive current is up to 0.6A for one channel.

### 2. Input logic

The MP6513L is controlled using a PWM input interface, each output is controlled by a corresponding input pin.

The following truth table shows the control logic for MP6513L:

| IN1 | IN2 | OUT1 | OUT2 | Function (DC Motor) |
|-----|-----|------|------|---------------------|
| L   | L   | Z    | Z    | Coast               |
| L   | H   | L    | H    | Reverse             |
| H   | L   | H    | L    | Forward             |
| H   | H   | L    | L    | Brake               |

### 3. Setup Condition

- Preset power supply of 2.5V to 5.5V between VCC and GND pins on CN1 terminal.
- The connector AINPUT/BINPUT should be connected to input signals, and refer above table to find the corresponding control logic.
- The connector CN2/CN3 should be connected to the motor winding terminals. For a stepper motor, one winding should be connected to CN2(AOUT1/AOUT2), while the other should be connected to CN3(BOUT1/BOUT2).
- Turn on power supply.

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