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# LV8805SV

## Bi-CMOS LSI PC and Server Fan Motor Driver

### Overview

The LV8805SV is a motor driver for PC and server fans.

### Feature

- Direct PWM three-phase sensorless motor driver

### Specifications

**Absolute Maximum Ratings** at  $T_a = 25^\circ\text{C}$

Parameter	Symbol	Conditions	Ratings	Unit
$V_{CC}$ maximum supply voltage	$V_{CC\ max}$		16	V
VG maximum supply voltage	VG max		21	V
OUT pin withstand voltage	$V_{OUT\ max}$		16	V
OUT pin maximum output current	$I_{OUT\ max}$	UO pin, VO pin, WO pin	1.2	A
SOFTST pin withstand voltage	$V_{SOFTST\ max}$		6	V
FR pin withstand voltage	$V_{FR\ max}$		6	V
PWMIN pin withstand voltage	$V_{PWMIN\ max}$		6	V
FG output pin withstand voltage	$V_{FG\ max}$		16	V
FG pin output current	$I_{FG\ max}$		5	mA
RD output pin withstand voltage	$V_{RD\ max}$		16	V
RD pin output current	$I_{RD\ max}$		5	mA
Allowable Power dissipation 1	$P_d\ max1$	Independent IC	0.3	W
Allowable Power dissipation 2	$P_d\ max2$	Mounted on designated board *1	0.95	W
Operating temperature	$T_{opr}$		-40 to +95	$^\circ\text{C}$
Storage temperature	$T_{stg}$	*2	-55 to +150	$^\circ\text{C}$

\*1: When mounted on the designated 76.1mm × 114.3mm × 1.6mm, glass epoxy board (single-layer)

\*2: Do not exceed  $T_{jmax}=150^\circ\text{C}$ .

Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.

Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

# LV8805SV

## Allowable Operating Conditions at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
V <sub>CC</sub> supply voltage	V <sub>CC</sub>		6 to 15	V
SOFTST input voltage range	V <sub>SOFTST</sub>		0 to V <sub>REG</sub>	V
FR input voltage range	V <sub>FR</sub>		0 to V <sub>REG</sub>	V
MINSP input voltage range	V <sub>MINSP</sub>		0 to V <sub>REG</sub>	V

## Electrical Characteristics at Ta = 25°C, V<sub>CC</sub> = 12V, unless otherwise specified

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
Circuit current 1	I <sub>CC1</sub>			2.6	3.6	mA
<b>Charge pump block</b>						
Charge pump output voltage	V <sub>VG</sub>			17		V
<b>Regulator block</b>						
5V regulator voltage	V <sub>VREG</sub>		4.75	5	5.25	V
<b>Output on resistance</b>						
Sum of high-/low-side output transistor on resistance	R <sub>on (H+L)</sub>	I <sub>O</sub> = 0.7A, V <sub>CC</sub> = 12V, V <sub>G</sub> = 17V		1.2	2	Ω
<b>Startup oscillator (OSC) pin</b>						
OSC pin charge current	I <sub>OSCC</sub>			-2.5		μA
OSC pin discharge current	I <sub>OSCD</sub>			2.5		μA
<b>PWM input (PWMIN) pin</b>						
High-level input voltage range	V <sub>PWMINH</sub>		2.3		V <sub>REG</sub>	V
Low-level input voltage range	V <sub>PWMINL</sub>		0		1	V
Range of PWM input frequency	f <sub>PWMIN</sub>		15		60	kHz
<b>Forward/reverse switching pin</b>						
High-level input voltage range	V <sub>FRH</sub>	Order of current application : U <sub>OUT</sub> →V <sub>OUT</sub> →W <sub>OUT</sub>	2.3		V <sub>REG</sub>	V
Low-level input voltage range	V <sub>FRL</sub>	Order of current application : U <sub>OUT</sub> →W <sub>OUT</sub> →V <sub>OUT</sub>	0		1	V
<b>FG and RD output pins</b>						
FG output pin low-level voltage	V <sub>FG</sub>	When I <sub>O</sub> is 2mA		0.25	0.35	V
FG output pin leak voltage	I <sub>IFG</sub>	When V <sub>FG</sub> is 16V			1	μA
RD output pin low-level voltage	V <sub>RD</sub>	When I <sub>O</sub> is 2mA		0.25	0.35	V
RD output pin leak voltage	I <sub>LRD</sub>	When V <sub>RD</sub> is 16V			1	μA
<b>Current limiter circuit</b>						
Limiter voltage	V <sub>RF</sub>	Limit current set to 1A when R <sub>F</sub> is 0.25Ω.	0.225	0.25	0.275	V
<b>Constraint protection circuit</b>						
CT pin high-level voltage	V <sub>CTH</sub>		2.25	2.8	2.95	V
CT pin low-level voltage	V <sub>CTL</sub>		0.43	0.5	0.65	V
CT pin charge current	I <sub>CTC</sub>		-2.9	-2.5	-2.1	μA
CT pin discharge current	I <sub>CTD</sub>		0.21	0.25	0.32	μA
ICT charge/discharge ratio	R <sub>CT</sub>		7	10	13	
<b>Soft start circuit</b>						
Soft start releasing voltage	V <sub>SOFTST</sub>			2.5		V
SOFTST pin charge current	I <sub>SOFTST</sub>			0.6		μA
<b>Thermal protection circuit</b>						
Thermal protection circuit operating temperature	TSD	Design target *	150	180	210	°C

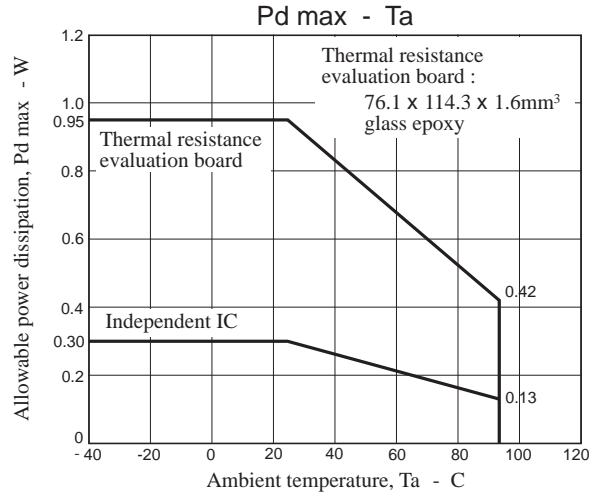
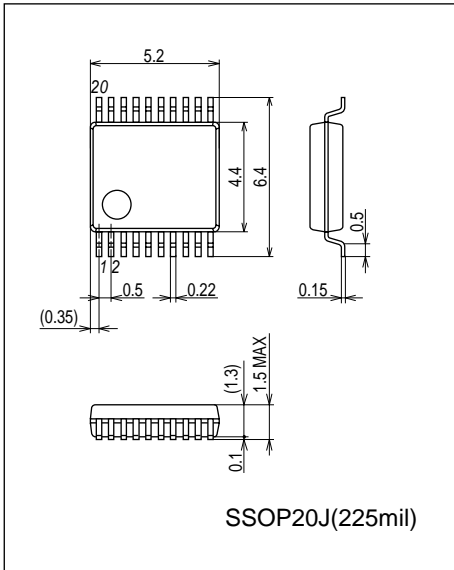
\* : Design target value and no measurement is made. The thermal protection circuit is incorporated to protect the IC from burnout or thermal destruction. Since it operates outside the IC's guaranteed operating range, the customer's thermal design should be performed so that the thermal protection circuit will not be activated when the fan is running under normal operating conditions.

# LV8805SV

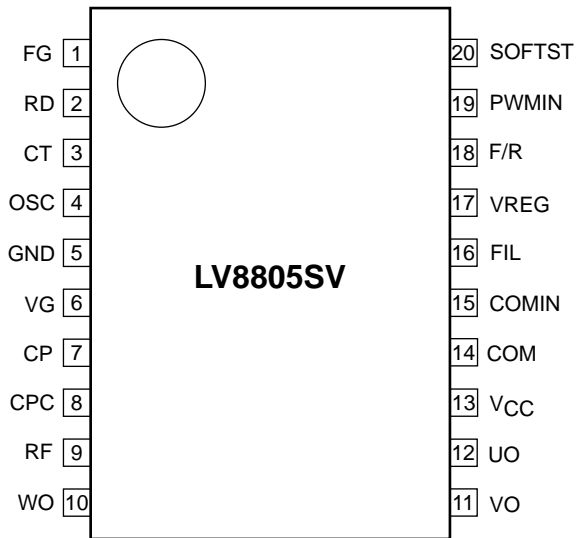
## Package Dimensions

unit : mm (typ)

3360



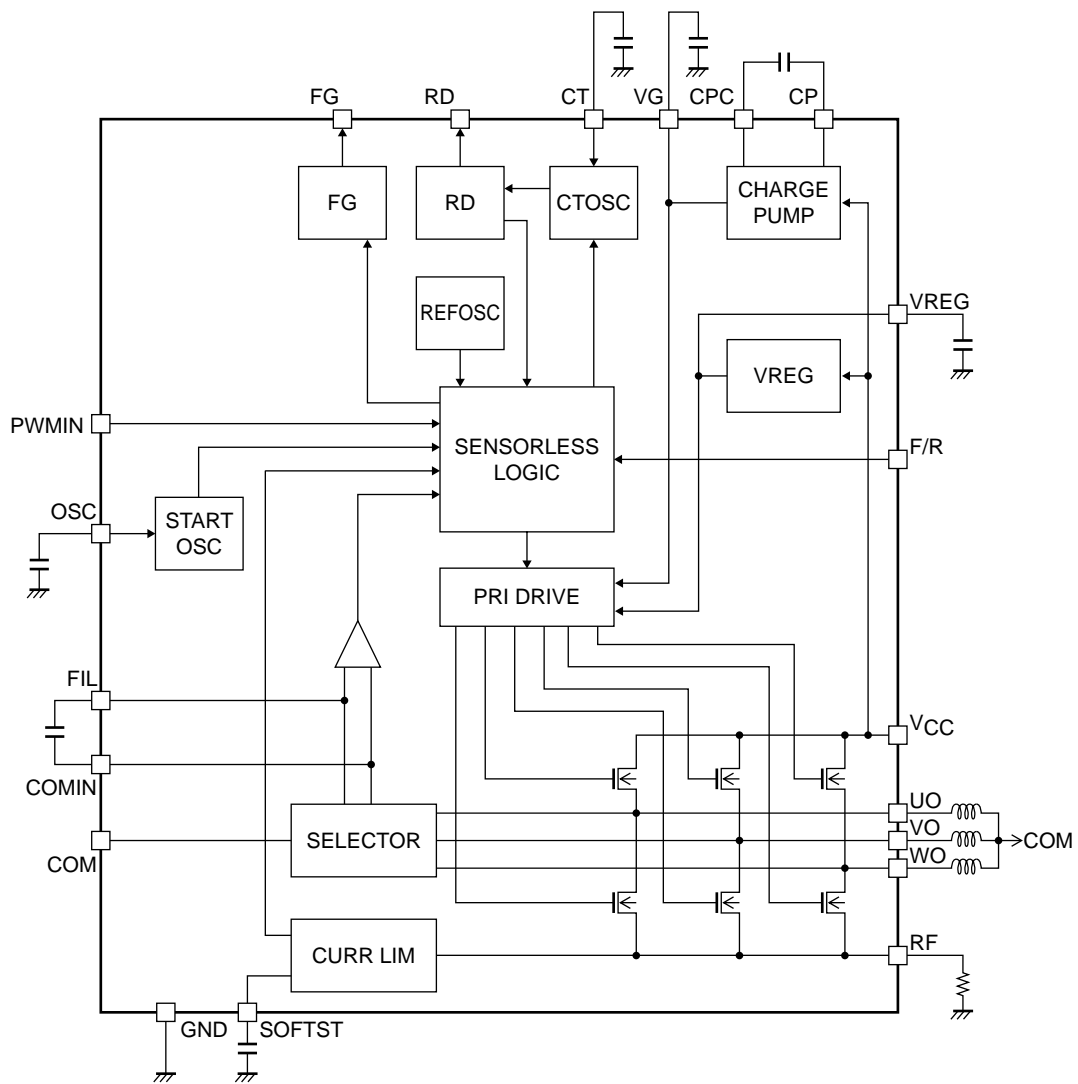
## Pin Assignment



Top view

# LV8805SV

## Block Diagram



# LV8805SV

## Pin Function

Pin No.	Pin name	Function	Equivalent circuit
1	FG	FG pulse output. This pin outputs a Hall sensor system equivalent pulse signal.	
2	RD	Motor lockup detection output. Output is fixed high when motor is locked up.	
3	CT	Motor lockup detection time setting. When the motor lockup condition is detected, the protection time period before the protection circuit is activated is set by connecting a capacitor between this pin and ground.	
4	OSC	Motor startup frequency setting. A capacitor must be connected between this pin and ground. The startup frequency is adjusted by controlling the charge/discharge current and capacitance of the capacitor.	
5	GND	GND pin	
6	VG	Charge pump step-up voltage output. A capacitor must be connected between this pin and the V <sub>CC</sub> pin or ground.	
7	CP	Charge pump step-up pulse output pin. A capacitor must be connected between this pin and the CPC pin (pin 8).	
8	CPC	Charge pump step-up pin. A capacitor must be connected between this pin and the CP pin (pin 7).	
13	V <sub>CC</sub>	Power supply for the IC and motor. Capacitors must be connected between these pins and ground.	
12	UO	Output pins. Connect these pins to the U, V, and W of the motor coil.	
11	VO		
10	WO		
9	RF	Output current detection pins. The drive current is detected by connecting a resistor between these pins and ground.	

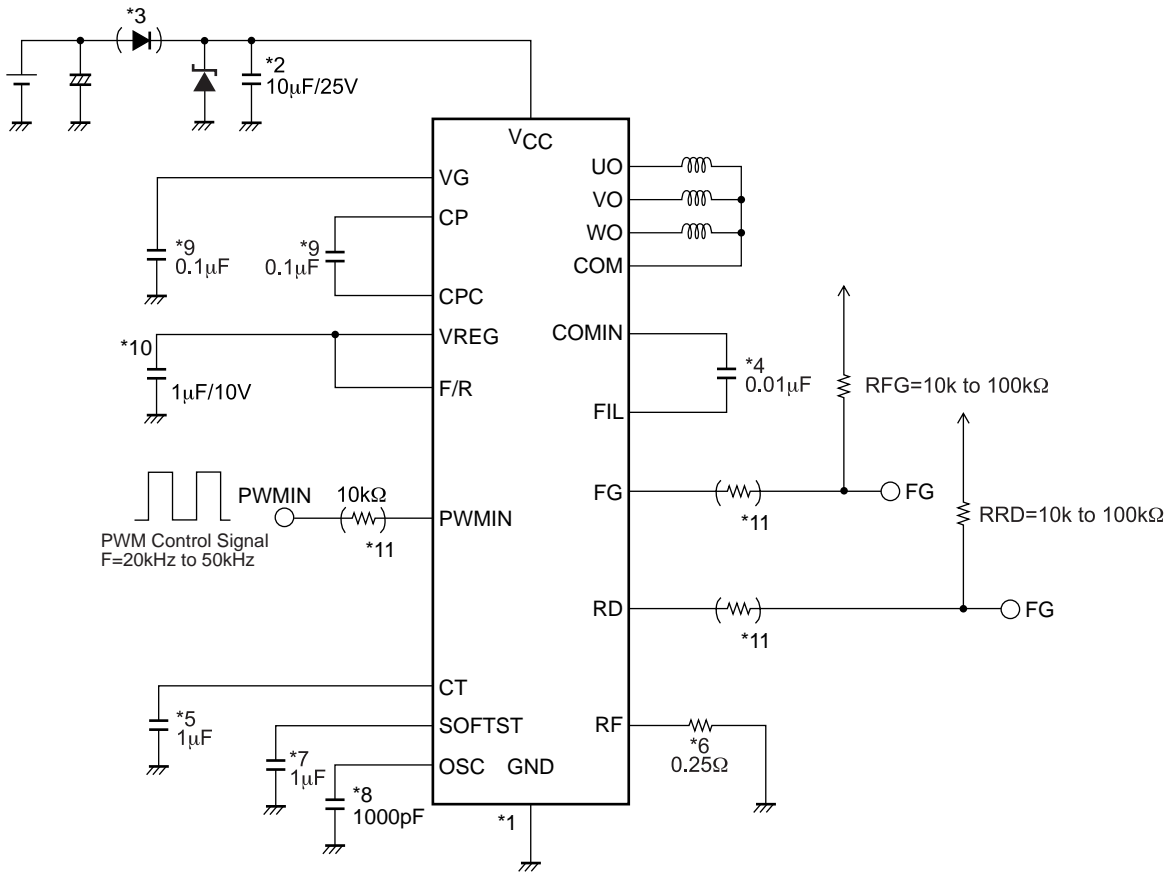
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# LV8805SV

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Pin No.	Pin name	Function	Equivalent circuit
14	COM	Motor middle point connection.	
15	COMIN	Motor position detection comparator filter pin. A capacitor must be connected between this pin and the FIL pin (pin 16).	
16	FIL	Motor position detection comparator filter pin. A capacitor must be connected between this pin and the COMIN pin (pin 15).	
17	VREG	Regulator voltage (5V) output. A capacitor must be connected between these pins and ground.	
18	F/R	Motor rotation direction switching. A high-level input causes current to flow into the motor in the order of U, V, and W and a low-level input in the order of U, W, and V. Changing the order of current application turns the motor in the opposite direction.	
19	PWMIN	PWM signal input pin. "H" The output transistor is turned on by the level voltage input. "L" The output transistor is turned off by the level voltage input, and the motor stops. The speed of the motor is controlled by controlling Duty of the input signal. When the pin opens, the motor becomes all velocities.	
20	SOFTST	Soft start time setting. The motor can be started smoothly by connecting a capacitor between this pin and ground.	

## Application Circuit Example



**\*1. Power supply and GND wiring**

The GND is connected to the control circuit power supply system.

**\*2. Power-side power stabilization capacitor**

For the power-side power stabilization capacitor, use a capacitor of 10µF or more.

Connect the capacitor between VCC and GND with a thick and along the shortest possible route.

LV8805SV uses synchronous rectification for high efficiency drive. Synchronous rectification is effective for heat reduction and higher efficiency. However, it may increase supply voltage.

If the supply voltage shall increase, make sure that it does not exceed the maximum ratings by inserting a zener diode between power supply and GND.

**\*3. Reverse connection protection diode**

This diode protects reverse connection.

Insert a diode between power supply and VCC pin to protect the IC from destruction due to reverse connection.

Connection of this diode is not necessary required.

**\*4. COMIN and FIL pins**

These pins are used to connect the filter capacitor. The LV8804 uses the back EMF signal generated when the motor is running to detect the information on the rotor position. The IC determines the timing at which the output block applies current to the motor based on the position information obtained here. Insert a filter capacitor with a capacitance ranging from (1,000pF to 10,000pF) between the COMIN pin and FIL pin to prevent any motor startup missoperation that is caused by noise. However, care must be taken since an excessively high capacitance will give rise to deterioration in efficiency and delays in the output power-on timing while the motor is running at high speed. Furthermore, connect the capacitor between the COMIN pin and FIL pin as close as possible in order to avoid the effects of noise from other sources.

**\*5. CT pin**

This pin is used to connect the lock detection capacitor.

The constant-current charging and constant-current discharging circuits incorporated causes locking when the pin voltage reaches 2.5V, and releasing the lock protection when it drops to 0.5V. This pin must be connected to the GND when it is not going to be used.

**\*6. RF pins**

These pins are used to set the current limit.

When the pin voltage exceeds 0.25V, the current is limited, and regeneration mode is established. In the application circuit, this voltage is set in such a way that the current limit will be established at 1A.

The calculation formula is given below.

RF resistance = 0.25V/target current limit value

**\*7. SOFTST pin**

This pin is used to set the soft start.

By connecting a capacitor between this pin and GND, the motor speed can be increased gradually.

When the pin voltage exceeds 2.5V, the soft start is released, and the LV8804V is switched to normal control.

If the soft start function is not going to be used, connect the pin to the VREG pin.

**\*8. OSC pin**

This pin is used to connect the capacitor for setting the startup frequency.

A capacitor with a capacitance ranging from about 500pF to 2,200pF (recommendation) must be connected between this pin and GND.

The OSC pin determines the motor startup frequency, so be sure to connect a capacitor to it.

<How to select the capacitance>

Select a capacitance value that will result in the shortest possible startup time for achieving the target speed and produce minimal variations in the startup time. If the capacitance is too high, variations in the startup time will increase; conversely, if it is too low, the motor may idle. The optimum OSC constant depends on the motor characteristics and startup current, so be sure to recheck them when the type of motor used or circuit specifications are changed.

**\*9. VG, CP, and CPC pins**

These pins are used to connect the capacitors to generate the pre-drive voltage and stabilize the pre-drive power supply.

Be sure to connect these capacitors in order to generate the drive voltage for the high-side (upper) output DMOS transistor.

**\*10. VREG pins**

These are the control system power supply pin and regulator output pin, which create the power supply of the control unit. Be sure to connect a capacitor between this pin and GND in order to stabilize control system operation.

Since these pins are used to supply current for control and generate the charge pump voltage, connect a capacitor with a capacitance that is higher than that of the capacitor connected to the charge pump.

Both the VREG pins (pins 3 and 4) must be short-circuited on the print pattern.

**\*11. Pin protection resistor**

It is recommended that resistors higher than 1k $\Omega$  are connected serially to protect pins against misconnection such as GND open and reverse connection.



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